

NOS Workshop

Ames Research Center Pilot Project: 'Tip' and 'Cue' Architectures for The New Observing System

February 2020

Motivation: Oroville Dam

i.e. Why you want an accurate
Quantitative Precipitation
Estimates (QPEs)

Dam operators were required
to discharge water based on
charts contained in the
*Oroville Dam Reservoir
Regulation Manual (1970)*

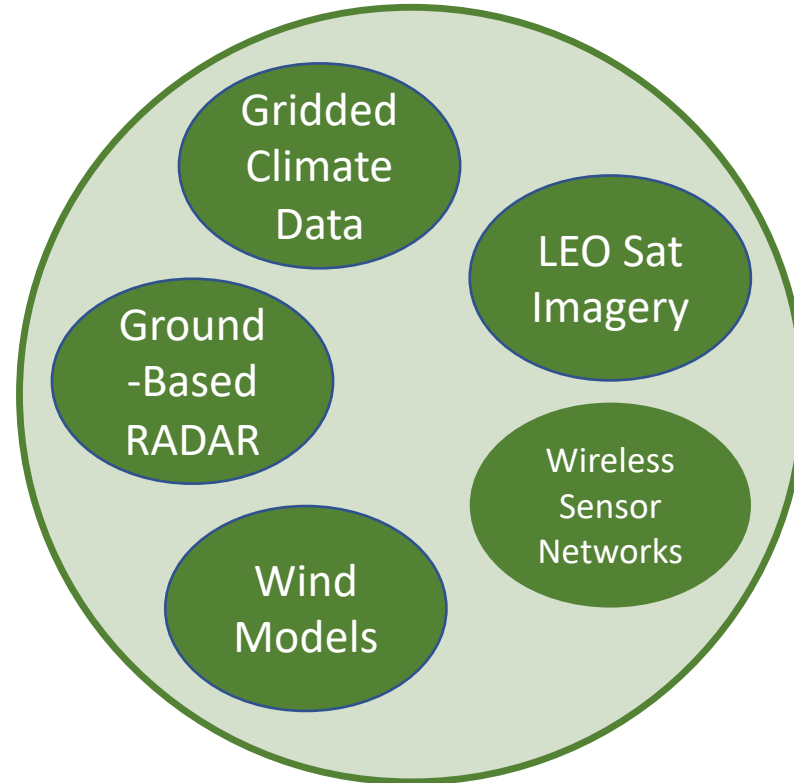
Accurate, timely estimates ->
better discharge predictions -
> avoiding catastrophes



Static vs. Dynamic Resources

Static Resources

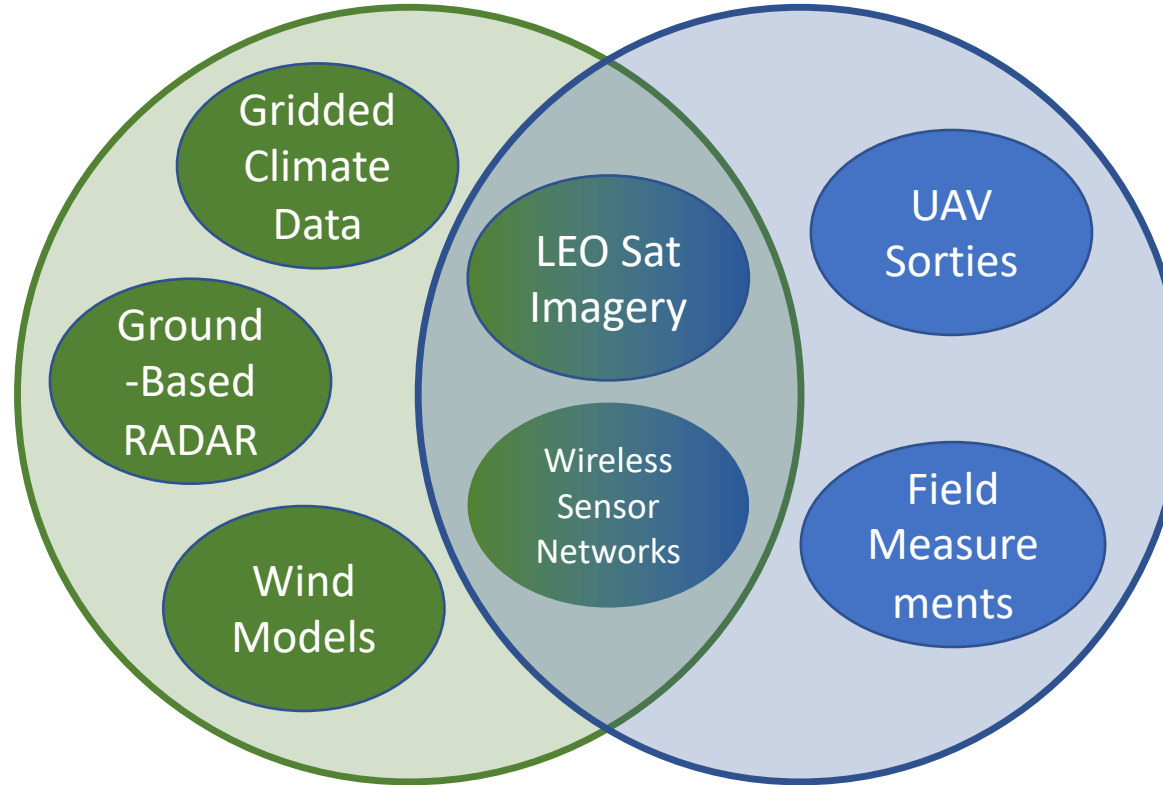
- Fixed scope
- Fixed Resources
- Cost amortized over many users
- Low Data Volumes over a large area



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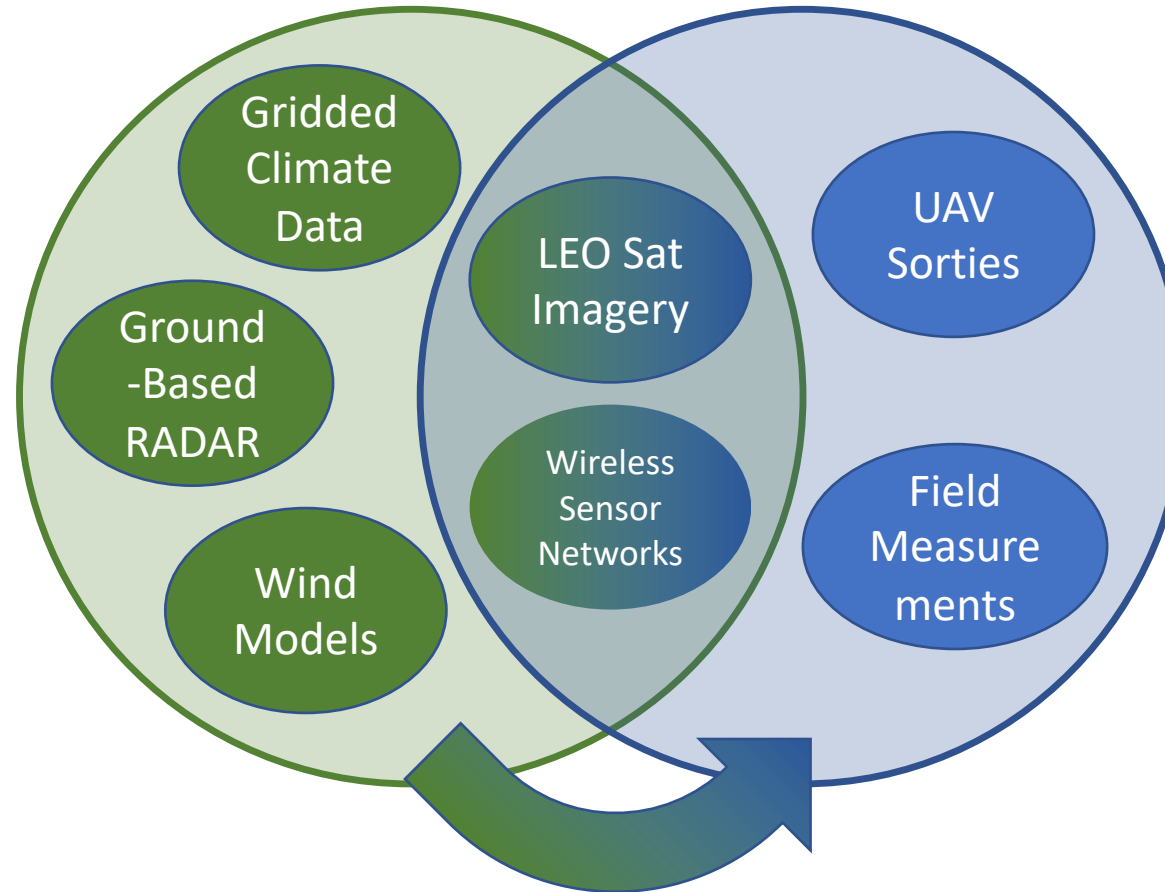
Dynamic Resources

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- Resource constrained = must prioritize observations
- Coverage can respond to new events
- High data volumes over a small area

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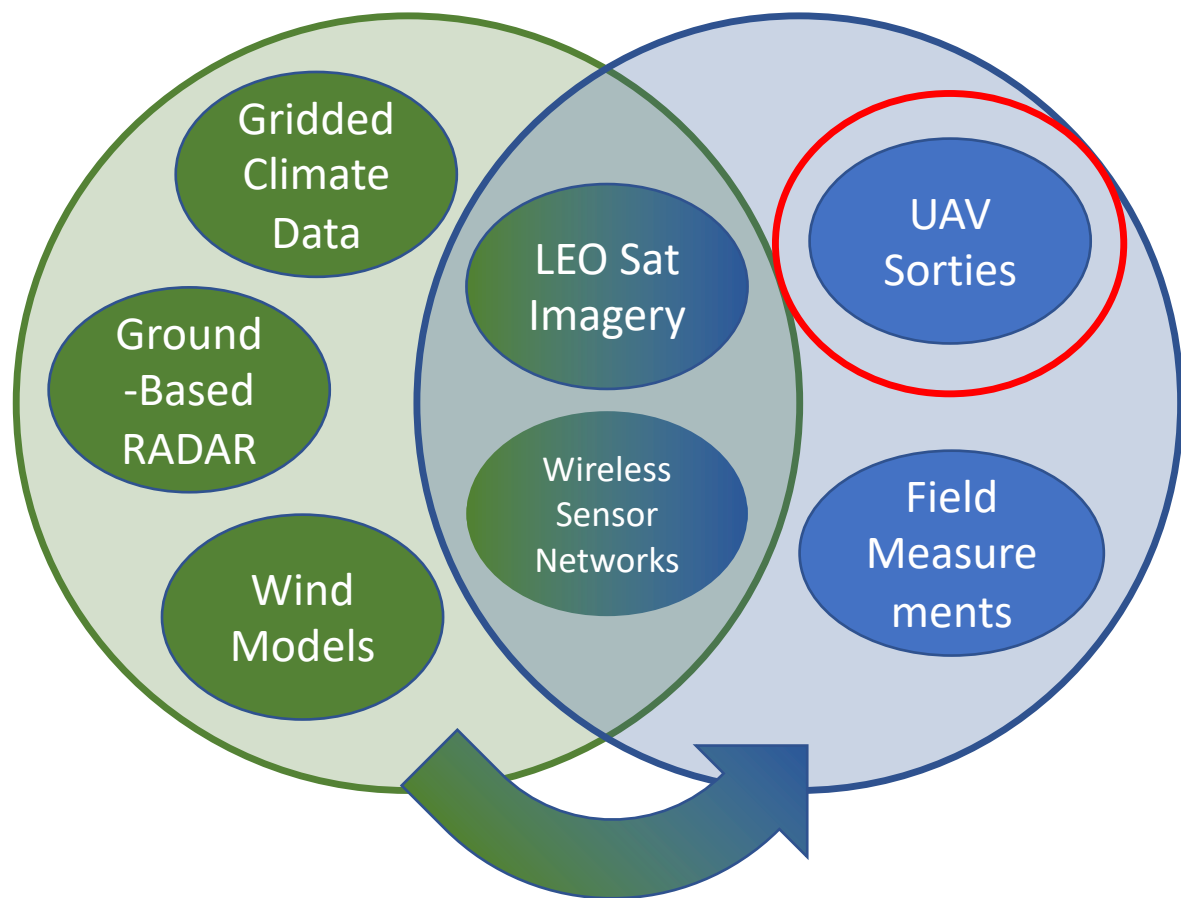


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Static Data Sources Identify Events (tip) and Deploy (cue) **Dynamic Data Sources** with Targeted Observation Campaigns

Static vs. Dynamic Resources

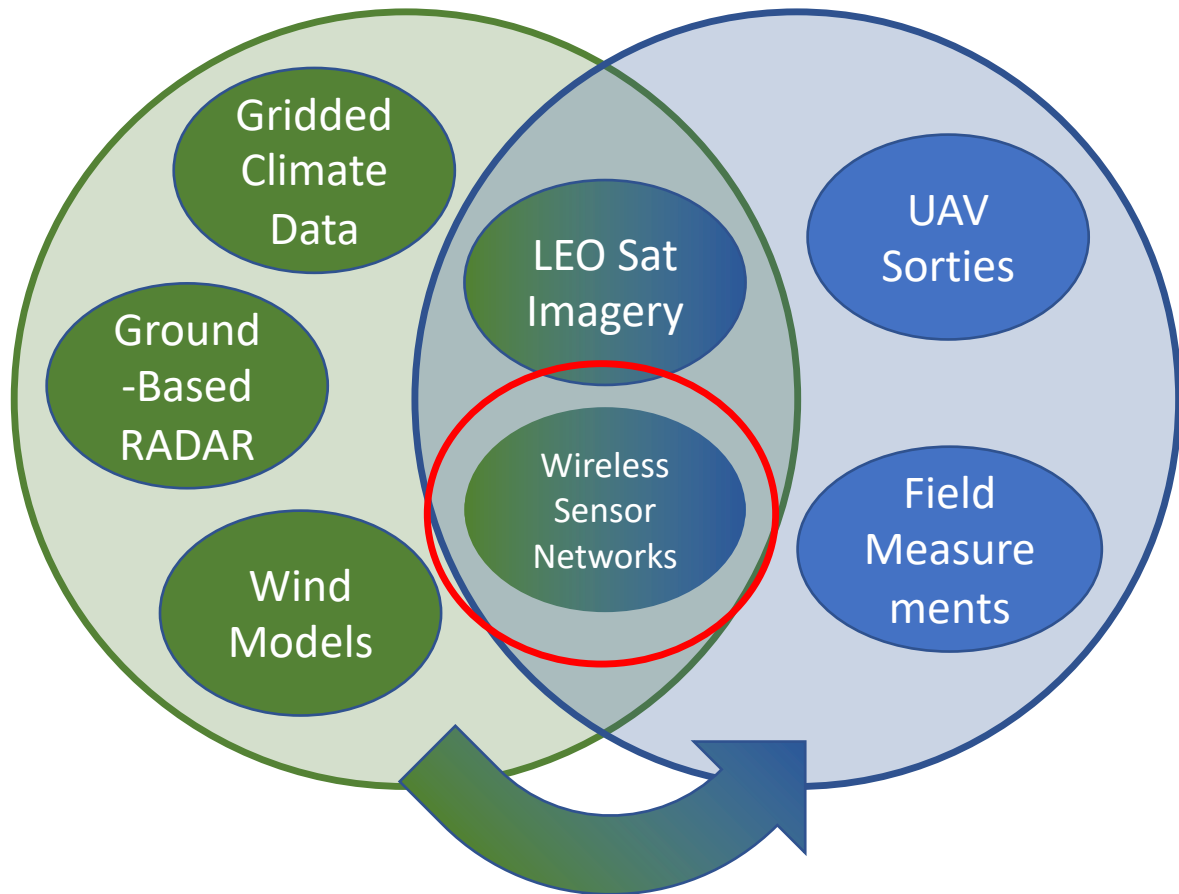


The USGS NextGen Water Observing System (NGWOS) will integrate “improved bidirectional comms for sensors nodes” and “integrated mobile monitoring assets”

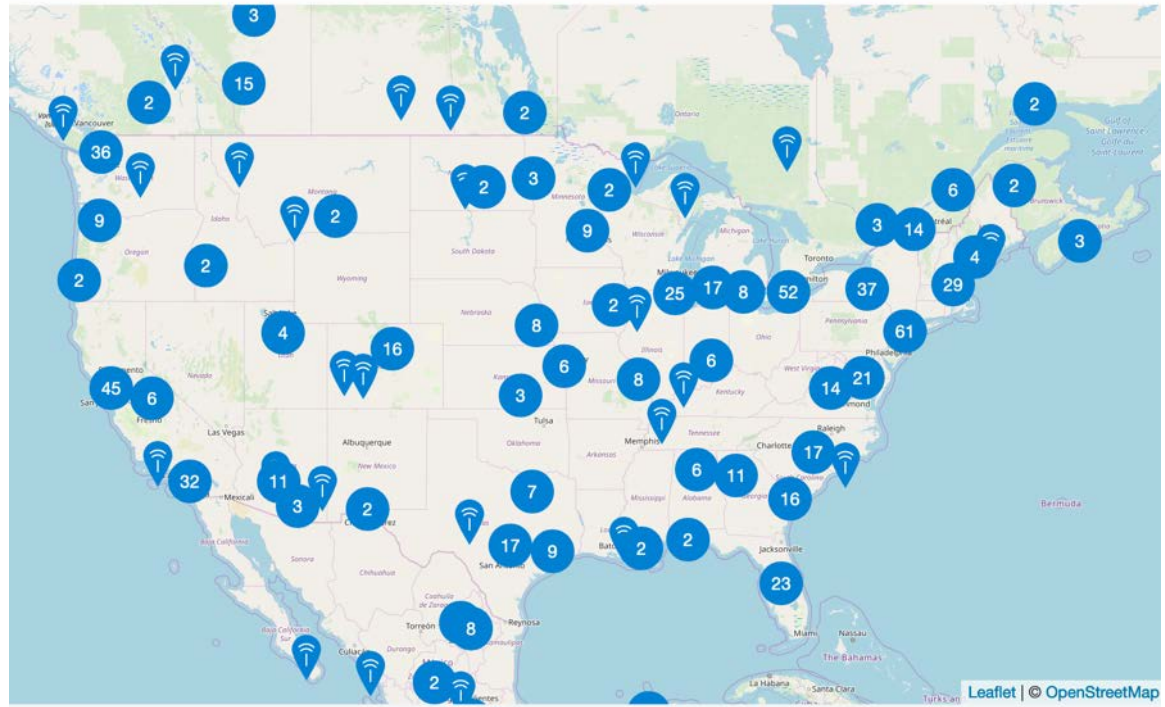


Mapping river water depth by using a drone-mounted ground-penetrating radar system (white equipment). (Credit: John W. Lane, USGS)

Static vs. Dynamic Resources



At this moment, there are 10830 gateways up and running



Massive private/crowdsourced buildout of shared RF infrastructure called the **Internet of Things**

Open Questions in Research

Question:

How can we have enough advance warning to prepare/deploy dynamic observations?

When is an impending event going to occur?

How can we best supplement existing static resources to provide the most accurate estimates?

Where do the assets go?

Technologies



Interfaces to/from forecast tools & "global data sources" (e.g. SSMIS IWV data products)



Rapid prototyping tools for testing new state estimation and tasking algorithms

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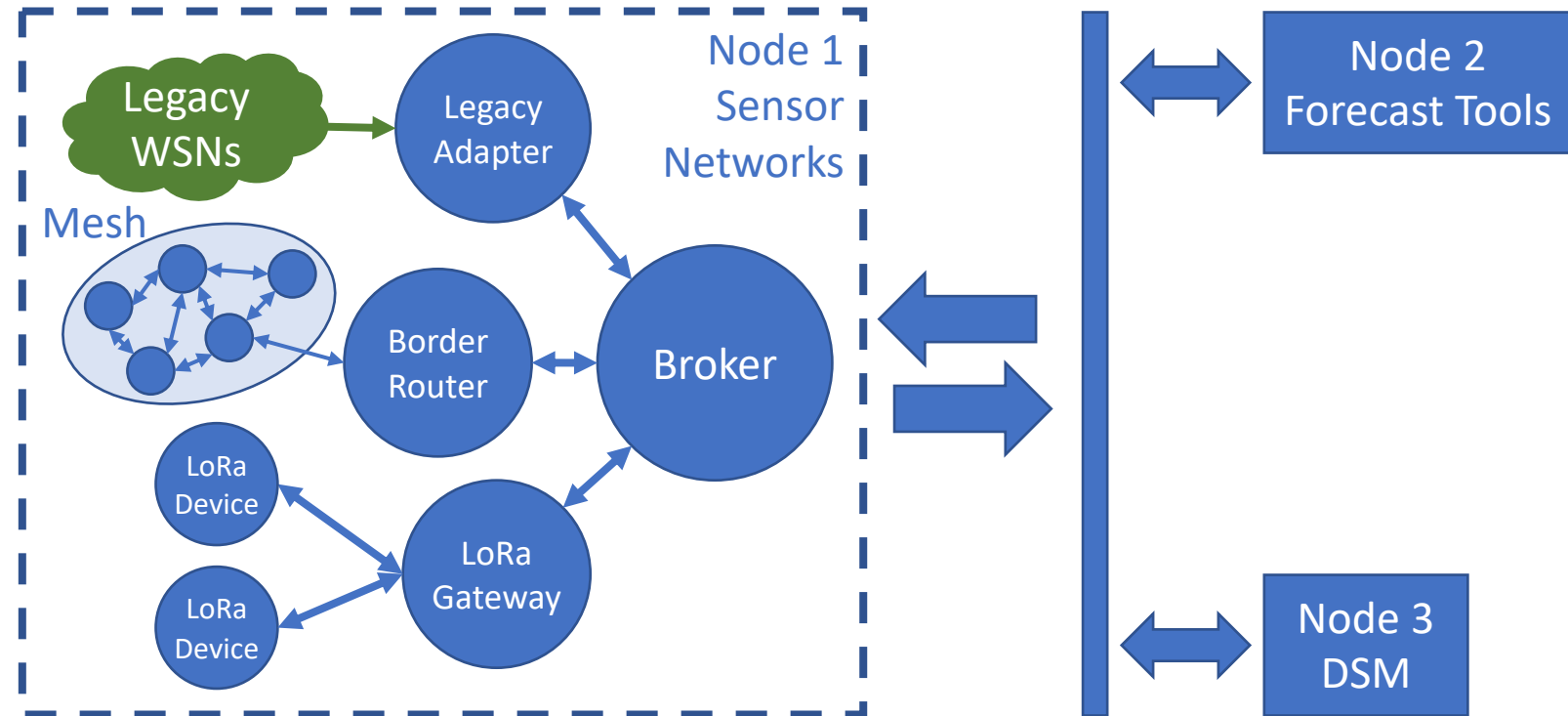


Rapid prototyping tools for testing new state estimation and tasking algorithms

Model-driven Measurement Acquisition

A broker provides the primary tasking interface between sensor networks with varying network topologies and capabilities, and other nodes in NOS-T

Implements
standards/ontologies in order to provide sensor networks as a service



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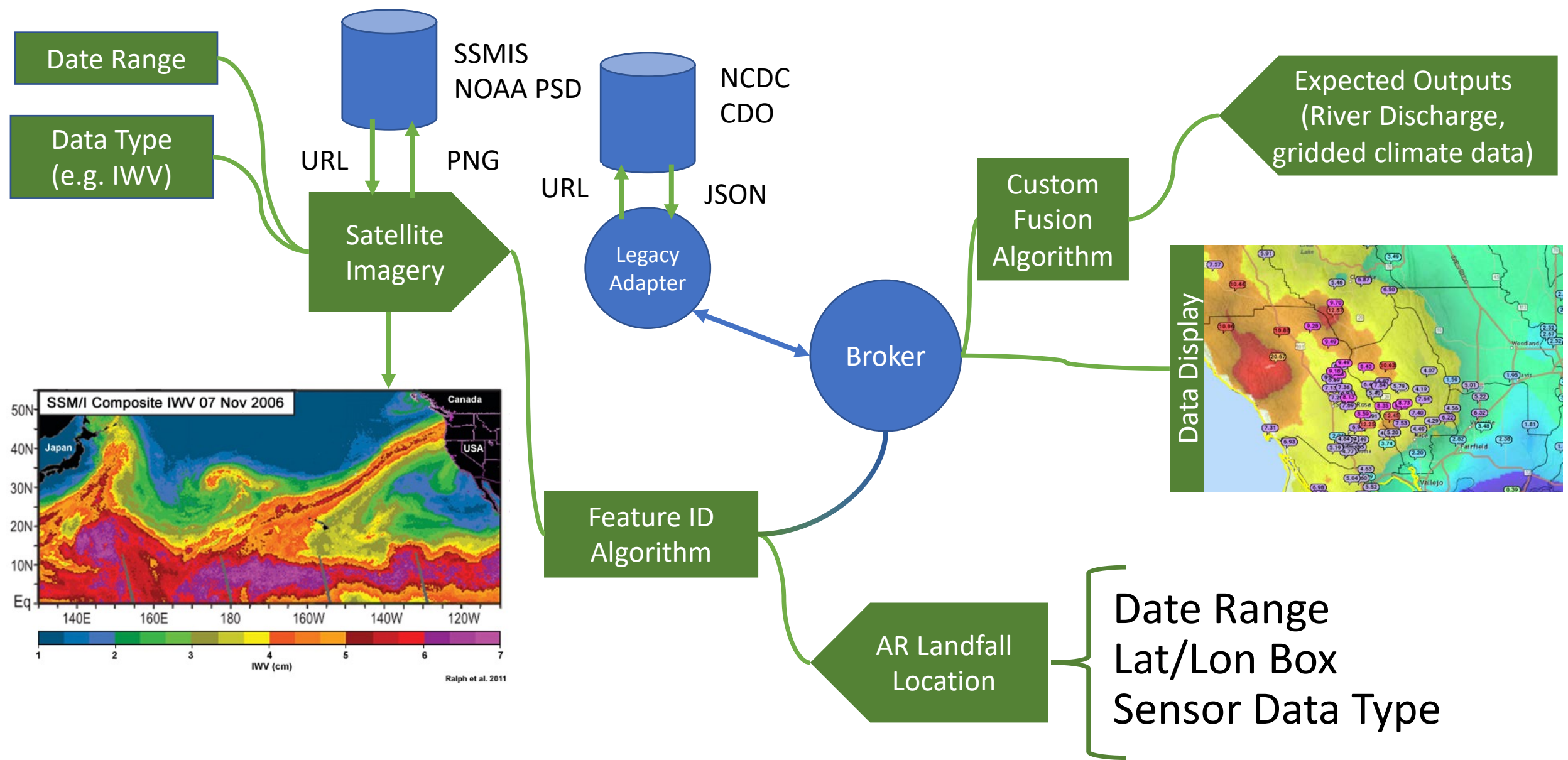


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Rapid prototyping tools for testing new state estimation and tasking algorithms

Event-Driven Measurement Acquisition



Open Questions

- What is the most effective way to integrate new techniques and data sources in a way that enables rapid prototyping?
- What kinds of time-sensitive, objective-oriented retasking can bring real science value to stakeholders?

Thank you!